

**Amendments to the Claims:**

This listing of claims will replace all prior versions, and listings of claims in the application:

**Listing of Claims:**

1. (Original) A method for visualising a spatially resolved data set (D) using an illumination model (BM), with a datum ( $D(\alpha, \beta, \gamma)$ ) of the data set (D) being associated in each case with a volume element (V) whose position is described by coordinates ( $\alpha, \beta, \gamma$ ) in a measurement coordinate system ( $K_m$ ), with the data ( $D(\alpha, \beta, \gamma)$ ) being loaded as at least one texture ( $T\alpha_i, T\beta_j, T\gamma_k$ ) into graphics hardware in order to generate a pictorial representation (5) in a projection space, characterised in that the illumination model (BM) is evaluated in the measurement coordinate system ( $K_M$ ).

2. (Original) A method in accordance with claim 1, in which the data ( $D(\alpha, \beta, \gamma)$ ) of the data set (D) are processed without transformation from the measurement coordinate system ( $K_M$ ) into another coordinate system, in particular without transformation into a Cartesian and/or isotropic coordinate system.

3. (Currently Amended) A method in accordance with ~~any one of the preceding claims~~ claim 1, in which the measurement coordinate system ( $K_M$ ) is a non-Cartesian measurement coordinate system ( $K_M$ ).

4. (Currently Amended) A method in accordance with ~~any one of the preceding claims~~ claim 1, in which the measurement coordinate system ( $K_M$ ) is a cylindrical system or a spherical coordinate system ( $K_M$ ).

5. (Currently Amended) A method in accordance with ~~any one of the preceding claims~~ claim 1, in which linear interpolation is carried out between the data ( $D(\alpha, \beta, \gamma)$ ) of the data set (D) in the measurement coordinate system ( $K_M$ ).

6. (Currently Amended) A method in accordance with ~~any one of the preceding claims~~ claim 1, in which the illumination model in the data set (D) is evaluated close to a singularity.

7. (Currently Amended) A method in accordance with ~~any one of the preceding claims~~ claim 1, in which the data ( $D(\alpha, \beta, \gamma)$ ) of the data set (D) represent a volume resolved scan of a body ( $G_0$ ); and in which the pictorial representation (5) is a three-dimensional representation (5), in particular a semi-transparent representation (5), of the body ( $G_0$ ).

8. (Currently Amended) A method in accordance with ~~any one of the preceding claims~~ claim 1, in which the pictorial representation (5) is generated as a stereoscopic projection.

9. (Currently Amended) A method in accordance with ~~any one of the preceding claims~~ claim 1, in which the data ( $D(\alpha, \beta, \gamma)$ ) of the data set (D) are generated by means of an ultrasonic measuring device (1).

10. (Currently Amended) Use of a method in accordance with ~~any one of the preceding claims~~ claim 1, in particular for medical purposes, for the fast generation of three-dimensional representations (5) of a body ( $G_0$ ), in particular of a human body or parts thereof, with reference to data ( $D(\alpha, \beta, \gamma)$ ) gained by a technical measurement.